

Release Notes for URCaps Plug-In GRIPKIT-EASY

1 General Release Notes

Third-party compatibility

The GRIPKIT-EASY URCaps Plug-In has been developed with a focus on performance and stability to meet highest standards. If you intend to install more URCaps plug-ins from different vendors next to the GRIPKIT-EASY Plug-In on your robot, please make sure the performance of the robot system is sufficient. Due to the internal architecture of the Universal Robots controller, different plug-ins may interfere causing unexpected malfunction. WEISS ROBOTICS cannot control the behavior of third-party plug-ins and recommends to run suitable tests at an early stage of application development. If in doubt, please contact our technical support before integrating GRIPKIT-EASY into your robot application.

Used resources

The GRIPKIT-EASY URCaps Plug-In requires exclusive access to the robot's Tool I/O interface. No other tools can be connected to the robot's flange port while using GRIPKIT-EASY.

2 Version-specific Release Notes

Release 1.1.0 - October 23, 2020

- System Requirements:
 - Requires at least PolyScope 5.9 (e-Series) or PolyScope 3.14 (CB-Series)
 - Tested up to PolyScope 5.9.1 (e-Series) and PolyScope 3.14.1 (CB-Series)
- Added UR's gripper driver to control the gripper via integrated UR functions.

Release 1.0.0 - December 9, 2019

- Initial software release
- System Requirements:
 - Requires at least PolyScope 5.5 (e-Series) or PolyScope 3.11 (CB-Series)
 - Tested up to PolyScope 5.5 (e-Series) and PolyScope 3.11 (CB-Series)