

## **Release Notes for URCaps Plug-In GRIPLINK**

### **1 General Release Notes**

#### **Third-party compatibility**

The GRIPLINK URCaps Plug-In has been developed with a focus on performance and stability to meet highest standards. If you intend to install other URCaps plug-ins from different vendors next to the GRIPLINK Plug-In on your robot controller, please make sure the performance of the robot system is sufficient. Due to the internal architecture of the Universal Robots controller, different plug-ins may interfere causing unexpected malfunction. WEISS ROBOTICS cannot control the behavior of third-party plug-ins and recommends to run suitable tests at an early stage of application development. If in doubt, please contact our technical support before integrating GRIPLINK-Et4 into your robot application.

#### **Used resources**

The GRIPLINK URCaps Plug-In uses the socket messaging communication functions provided by the robot controller to communicate with the GRIPLINK-ET4 and connected devices. Therefore, the Plug-In uses the robot controller's TCP/IP port 10001/TCP. Please make sure that no other plug-in or robot program makes use of this port.

### **2 Version-specific Release Notes**

#### **Release 1.0.0 – March 14, 2022**

- System Requirements:
  - Requires at least PolyScope 5.4 (e-Series) or PolyScope 3.10 (CB-Series)
  - Tested up to PolyScope 5.9 (e-Series) and PolyScope 3.14 (CB-Series)
- First implementation.